Dynamical Isometry is Achieved in Residual Networks in a Universal Way for any Activation Function

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Deep Learning



Johnny von Neumann: with four parameters I can fit an elephant, and with five I can make him wiggle his trunk.

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"Drawing an elephant with four complex parameters" by Jurgen Mayer, Khaled Khairy, and Jonathon Howard, Am. J. Phys. 78, 648 (2010), DOI:10.1119/1.3254017.

State-of-the-art deep neural nets sometimes contain millions or even billions of parameters!

Fundamental:

- Massive over parametrization... so why don't deep NN overfit?
- ...

Technical:

- What activation functions to use?
- How to train more efficiently
- How to initialize?
- How to choose architecture?
- ...

Practical:

- Explainability
- Robustness

• . . .

We tackle the problem of initialization of deep Residual Neural Networks with Random Matrix and Free Probability Theories.

This is done by making sure the singular spectrum of the input-output Jacobian is concentrated around one. This is called dynamical isometry.

$$J_{ik} = \frac{\partial x_i^L}{\partial x_k^0}$$

Presentation plan:

- (Deep) artificial neural networks a short introduction
- The problem in short
- Stating the problem in more detail
- The case of Feed Forward Networks
- What we find for ResNets





Signal propagation:

 $\mathbf{x}^{\mathbf{l}} = \phi(\mathbf{h}^{\mathbf{l}}), \quad \mathbf{h}^{\mathbf{l}} = \mathbf{W}^{\mathbf{l}}\mathbf{x}^{\mathbf{l-1}} + \mathbf{b}^{\mathbf{l}}$

L - number of layers in the network



Question: Can we say sth about how weights (bias) initialization will effect learning?

 $\Delta W_{ij}^l = -\eta \frac{\partial E(\boldsymbol{x}^L, \boldsymbol{y})}{\partial W_{ij}^l}$

The learning process is based on gradually modifying the weights of the network

$$\Delta W_{ij}^{l} = -\eta \sum_{k,t} \frac{\partial x_{t}^{l}}{\partial W_{ij}^{l}} \frac{\partial x_{k}^{L}}{\partial x_{t}^{l}} \frac{\partial E(\boldsymbol{x}^{L}, \boldsymbol{y})}{\partial x_{k}^{L}}$$

All the terms in the sum of products must be bounded

$$J_{ik} = \frac{\partial x_i^L}{\partial x_k^0}$$

The input-output Jacobian is the most problematic one

It can be rewritten as:

$$\boldsymbol{J} = \prod_{l=1}^{L} \left(\boldsymbol{D}^{l} \boldsymbol{W}^{l} \right), \quad \text{with} \quad D_{ij}^{l} = \phi'(h_{i}^{l}) \delta_{ij}$$

For a given activation function and network depth L, how to initialize the weights?



The case of Feed Forward Networks

(2017, Pennigton et al.)

Activation function:
$$\phi(h) = anh(h)$$

Weight matrix at initialization orthogonal: $W^TW = \mathbf{1}$

Fixed point related to signal propagation.

Dynamical Isometry in feed forward neural network

"Orders of magnitude" faster learning of DEEP feed forward neural networks. Training of 10000 layer vanilla CNN.

Not possible at all for ReLU (in feed forward networks).



(a slightly more sophisticated version outmatched other models in the 2015 ILSVRC and COCO competitions)



Question: Can we say sth about how weights (bias) initialization will effect learning?

For a given activation function and network depth L, how to initialize the weights?

Use Random Matrix and Free Probability Theories to find the singular values of

$$\boldsymbol{J} = \prod_{l=1}^{L} \left(\boldsymbol{D}^{l} \boldsymbol{W}^{l} + \mathbf{1} \boldsymbol{a} \right), \quad \text{with} \quad \boldsymbol{D}_{ij}^{l} = \phi'(h_{i}^{l}) \delta_{ij}$$

Study Signal propagation in the network to find the statistics of

• Rapid introduction to RMT

Random Matrix Theory
$$G_H(z) = \left\langle \frac{1}{N} \operatorname{Tr} (z\mathbf{1} - H)^{-1} \right\rangle = \int_{-\infty}^{\infty} \frac{\rho_H(\lambda) d\lambda}{z - \lambda}$$

$$\rho_H(x) = -\frac{1}{\pi} \lim_{\epsilon \to 0} G_H(x + i\epsilon).$$

Free Probability Theory

$$G\left(R(z) + \frac{1}{z}\right) = z, \qquad R(G(z)) + \frac{1}{G(z)} = z.$$

$$R_{X+Y}(z) = R_X(z) + R_Y(z)$$
R-transform

$$S(zR(z)) = \frac{1}{R(z)}, \quad R(zS(z)) = \frac{1}{S(z)}.$$

$$S_{AB}(z) = S_A(z)S_B(z) \qquad S-\text{transform}$$

Singular spectrum of
$$J = \prod_{l=1}^{L} (D^l W^l + 1a)$$

Calculate $S_{JJ^T}(z) = \prod_{l=1}^{L} S_{Y_l Y_l^T}(z)$ then revert back to the Greens function

$$G(z) = \left\langle \frac{1}{N} \operatorname{Tr}(z\mathbf{1} - \mathbf{Y}_{l}\mathbf{Y}_{l}^{T})^{-1} \right\rangle \qquad \mathbf{Y}_{l} = (a\mathbf{1} + \mathbf{D}^{l}\mathbf{W}^{l}) \qquad \mathbf{X} = \mathbf{D}^{l}\mathbf{W}^{l}$$

Generalized resolvent

$$\mathcal{G} := \begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix} = \left\langle \frac{1}{N} \mathbf{b} \mathbf{Tr} \begin{pmatrix} -a - \mathbf{X} & 1 \\ z & -a - \mathbf{X}^T \end{pmatrix}^{-1} \right\rangle$$

$$\boldsymbol{\mathcal{Z}} := \begin{pmatrix} -a & 1 \\ z & -a \end{pmatrix}, \qquad \boldsymbol{\mathcal{X}} := \begin{pmatrix} \boldsymbol{X} & 0 \\ 0 & \boldsymbol{X}^T \end{pmatrix}$$

Generalized R-transform

$$\mathcal{G}(\mathcal{Z}) = (\mathcal{Z} - \mathcal{R}(\mathcal{G}(\mathcal{Z})))^{-1}$$

Singular spectrum of
$$J = \prod_{l=1}^{L} (D^l W^l + 1a)$$

$$c_2^l = \sigma_W^2 \left\langle \left(\phi'(h) \right)^2 \right\rangle_l = \sigma_W^2 \int \mathcal{D} z \phi'^2 \left(\sqrt{q^l} z \right)$$

define the effective cumulant: $c = \frac{1}{L} \sum_{l=1}^{L} c_2^l$

The large network depth limit (recall the scaling of the variance: $\sigma_w^2/(NL)$)

$$\ln S_{JJ^{T}}(z) = -2L\ln a + \sum_{l=1}^{L} \ln \left(1 - \frac{c_{2}^{l}}{a^{2}L} (1+2z) \right) \approx -2L\ln a - \frac{1+2z}{a^{2}L} \sum_{l=1}^{L} c_{2}^{l} =: -2L\ln a - \frac{(1+2z)}{a^{2}} c_{2}^{l}$$

$$S_{JJ^{T}}(z) = \frac{1}{a^{2L}}e^{-\frac{c}{a^{2}}(1+2z)}$$

Universal formula for any activation function!

$$a^{2L}G(z) = (zG(z) - 1)e^{\frac{c}{a^2}(1 - 2zG(z))}$$

(solution in terms of the Lambert function)

$$c_2^l = \left\langle \frac{1}{N} \operatorname{Tr} \boldsymbol{W}^l \boldsymbol{D}^l (\boldsymbol{W}^l)^T \right\rangle = \frac{\sigma_w^2}{N} \sum_i^N \left(\phi'(h_i^l) \right)^2 = \sigma_W^2 \int \mathcal{D} z \phi'^2 \left(\sqrt{q^l} z \right)$$

Signal propagation:
$$\mathbf{x^l} = \phi(\mathbf{h^l}) + \mathbf{ax^{l-1}}, \ \mathbf{h^l} = \mathbf{W^lx^{l-1}} + \mathbf{b^l}$$

elements of weight matrices and bias vectors - i.i.d. Gaussian with mean 0 and variances: $\sigma_w^2/(NL)~$ and σ_b^2

Study:
$$q^l = rac{1}{N_l}\sum_{i=1}^{N_l}(\mathbf{h}_i^l)^2$$

The resulting mapping:

$$q^{l+1} = a^2 q^l - \left(a^2 - 1\right)\sigma_b^2 + \frac{(\sigma_W)^2}{L} \int \mathcal{D}z\phi^2\left(\sqrt{q^l}z\right) + 2\frac{(\sigma_W)^2}{L} \left[\sum_{k=1}^{l-1} a^k \int \mathcal{D}z\phi\left(\sqrt{q^{l-k}}z\right)\right] \int \mathcal{D}z\phi\left(\sqrt{q^l}z\right) dz$$

Same result for orthogonal weight matrices.

$$c_2^l = \sigma_W^2 \left\langle (\phi'(h))^2 \right\rangle_l = \sigma_W^2 \int \mathcal{D} z \phi'^2 \left(\sqrt{q^l} z \right)$$

For example, in the case of the sigmoid activation function:

 $\phi(x) = \frac{1}{1 + e^{-x}}$



With a proper scaling of the variances of the weights, the result is a universal formula for the probability density of the singular values, depending on a single parameter c.



Corroborated with numerical experiments with neural networks with random inputs



Corroborated with numerical experiments with neural networks initialized on the CIFAR-10 dataset.

— Linear
Leaky ReLU α =0.05
— ReLU
— SELU
— Tanh
— HardTanh

— Sigmoid

These results allow us to eliminate the singular spectrum of the Jacobian treated as a confounding factor in experiments with the learning process of simple residual neural networks for different activation functions enabling meaningful comparisons.



To remember:

- Deep Neural Networks powerful but many aspects not understood
- A proper initialization can allow efficient training for VERY deep feedforward NN. This is facilitated by Dynamical Isometry.
- For ResNets Dynamical Isometry can be achieved for any activation functions, but remember about proper order of magnitude for variances.

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Random Matrices and Information Measures - SONATA project number 2016/21/D/ST2/01142.

Thank you for your attention.

